

Dane materiałowe

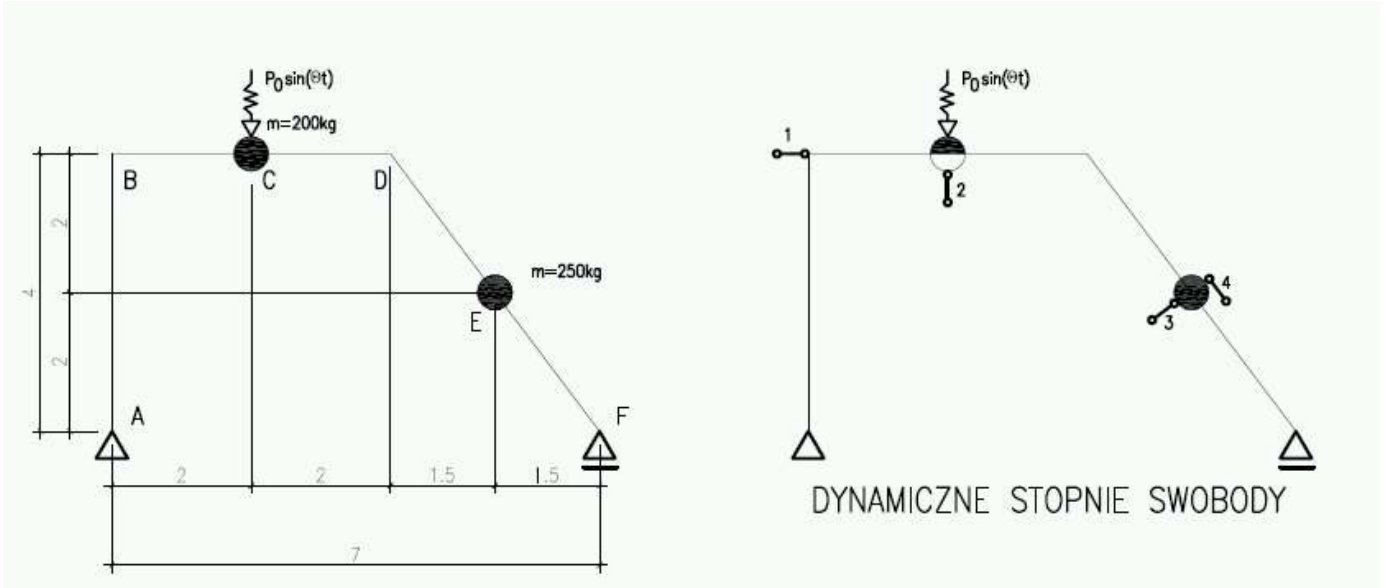
$E := 210 \cdot 10^6 \cdot \text{kPa}$ $h := 10\text{cm}$ $b := 24\text{cm}$

$J := \frac{b \cdot h^3}{12} = 2 \times 10^{-5} \cdot \text{m}^4$

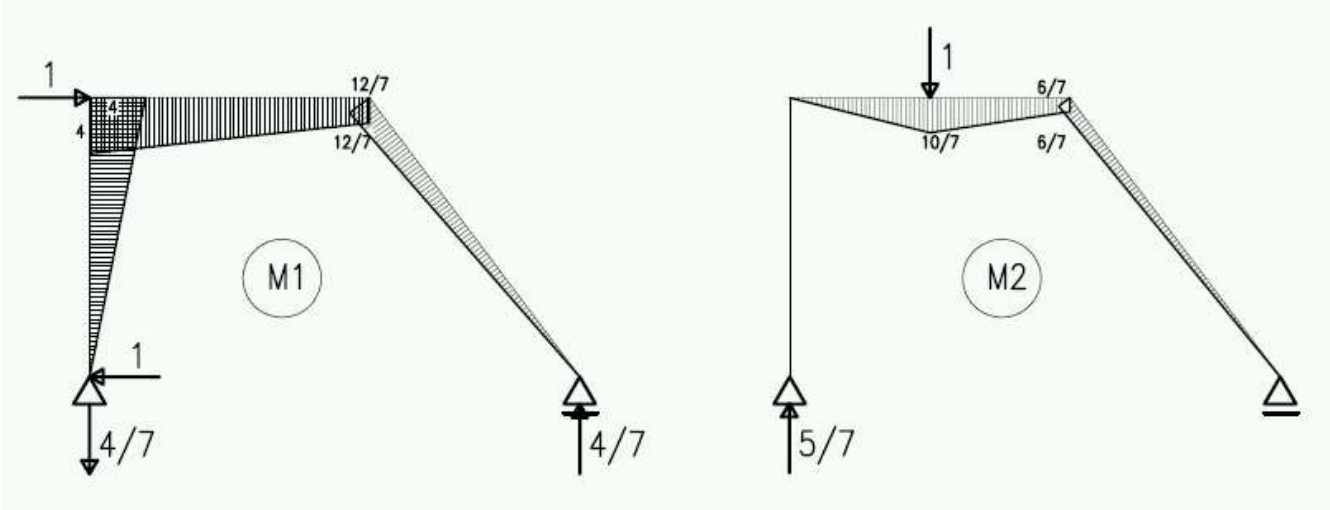
$EJ := E \cdot J = 4.2 \times 10^3 \cdot \text{kN} \cdot \text{m}^2$

$m_0 := 50 \cdot \text{kg}$

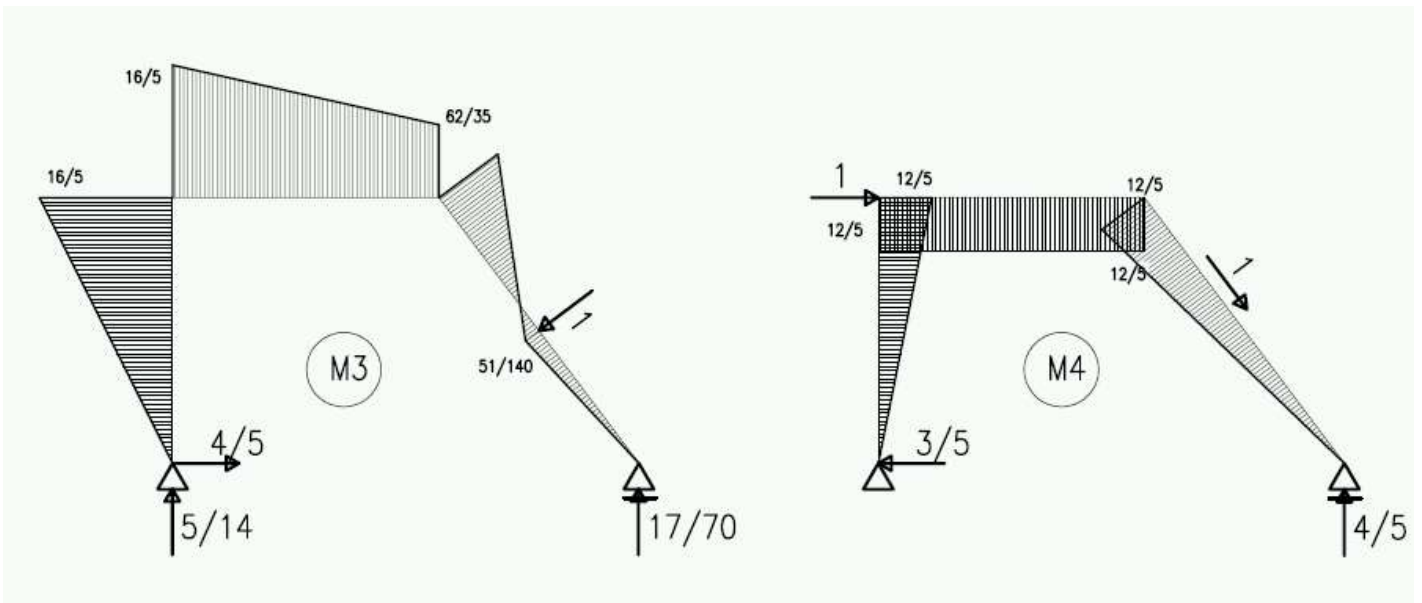
Schemat ustroju i dynamiczne stopnie swobody ustroju



Stan 1 (M1) oraz Stan 2 (M2)



Stan 3 (M3) oraz Stan 4 (M4)



Sprawdzenie delt z RM-WIN jako przemieszczenia na odpowiednich stopiach swobody

$$14.435\text{mm}\cdot\text{EJ} = 60.627\cdot\text{kN}\cdot\text{m}^3$$

$$2.954\text{mm}\cdot\text{EJ} = 12.407\cdot\text{kN}\cdot\text{m}^3$$

$$1.251\text{mm}\cdot\text{EJ} = 5.254\cdot\text{kN}\cdot\text{m}^3$$

$$-11.654\text{mm}\cdot\text{EJ} = -48.947\cdot\text{kN}\cdot\text{m}^3$$

$$-2.384\text{mm}\cdot\text{EJ} = -10.013\cdot\text{kN}\cdot\text{m}^3$$

$$9.845\text{mm}\cdot\text{EJ} = 41.349\cdot\text{kN}\cdot\text{m}^3$$

$$1.1211\text{cm}\cdot\text{EJ} = 47.086\cdot\text{kN}\cdot\text{m}^3$$

$$0.2939\text{cm}\cdot\text{EJ} = 12.344\cdot\text{kN}\cdot\text{m}^3$$

$$-0.8914\text{cm}\cdot\text{EJ} = -37.439\cdot\text{kN}\cdot\text{m}^3$$

$$0.96\text{cm}\cdot\text{EJ} = 40.32\cdot\text{kN}\cdot\text{m}^3$$

Obliczenia delt

$$d_{11} = (M_1 \cdot M_1) \quad d_{11} := \frac{1}{2} \cdot 4 \cdot 4 \cdot \frac{2}{3} \cdot 4 + \frac{1}{2} \cdot 4 \cdot 4 \left(\frac{2}{3} \cdot 4 + \frac{1}{3} \cdot \frac{12}{7} \right) + \frac{1}{2} \cdot \frac{12}{7} \cdot 4 \left(\frac{1}{3} \cdot 4 + \frac{2}{3} \cdot \frac{12}{7} \right) + \frac{1}{2} \cdot \frac{12}{7} \cdot 5 \cdot \frac{2}{3} \cdot \frac{12}{7} = 60.626$$

$$d_{12} = (M_1 \cdot M_2) \quad d_{12} := \frac{1}{2} \cdot 2 \cdot \frac{10}{7} \cdot \left(\frac{1}{3} \cdot 4 + \frac{2}{3} \cdot \frac{20}{7} \right) + \frac{1}{2} \cdot \frac{10}{7} \cdot 2 \left(\frac{2}{3} \cdot \frac{20}{7} + \frac{1}{3} \cdot \frac{12}{7} \right) \dots = 12.408$$

$$+ \frac{1}{2} \cdot 2 \cdot \frac{6}{7} \cdot \left(\frac{1}{3} \cdot \frac{20}{7} + \frac{2}{3} \cdot \frac{12}{7} \right) + \frac{1}{2} \cdot 5 \cdot \frac{12}{7} \cdot \frac{2}{3} \cdot \frac{6}{7}$$

$$d_{13} = (M_1 \cdot M_3) \quad d_{13} := \frac{-1}{2} \cdot 4 \cdot 4 \cdot \frac{2}{3} \cdot \frac{16}{5} - \frac{1}{2} \cdot 4 \cdot 4 \left(\frac{2}{3} \cdot \frac{16}{5} + \frac{1}{3} \cdot \frac{62}{35} \right) - \frac{1}{2} \cdot \frac{12}{7} \cdot 4 \left(\frac{1}{3} \cdot \frac{16}{5} + \frac{2}{3} \cdot \frac{62}{35} \right) \dots = -48.946$$

$$+ \frac{-1}{2} \cdot \frac{62}{35} \cdot \frac{5}{2} \cdot \left(\frac{2}{3} \cdot \frac{12}{7} + \frac{1}{3} \cdot \frac{6}{7} \right) + \frac{1}{2} \cdot \frac{51}{140} \cdot \frac{5}{2} \cdot \left(\frac{1}{3} \cdot \frac{12}{7} + \frac{2}{3} \cdot \frac{6}{7} \right) + \frac{1}{2} \cdot \frac{6}{7} \cdot \frac{5}{2} \cdot \frac{2}{3} \cdot \frac{51}{140}$$

$$d_{14} = (M_1 \cdot M_3) \quad d_{14} := \frac{1}{2} \cdot 4 \cdot 4 \cdot \frac{2}{3} \cdot \frac{12}{5} + \frac{1}{2} \cdot 4 \cdot 4 \cdot \frac{12}{5} + \frac{1}{2} \cdot 4 \cdot \frac{12}{7} \cdot \frac{12}{5} + \frac{1}{2} \cdot \frac{12}{7} \cdot 5 \cdot \frac{2}{3} \cdot \frac{12}{5} = 47.086$$

$$d_{22} = (M_2 \cdot M_2) \quad d_{22} := \frac{1}{2} \cdot \frac{10}{7} \cdot 2 \cdot \frac{2}{3} \cdot \frac{10}{7} + \frac{1}{2} \cdot \frac{10}{7} \cdot 2 \cdot \left(\frac{2}{3} \cdot \frac{10}{7} + \frac{1}{3} \cdot \frac{6}{7} \right) + \frac{1}{2} \cdot \frac{6}{7} \cdot 2 \cdot \left(\frac{1}{3} \cdot \frac{10}{7} + \frac{2}{3} \cdot \frac{6}{7} \right) + \frac{1}{2} \cdot \frac{6}{7} \cdot 5 \cdot \frac{2}{3} \cdot \frac{6}{7} = 5.252$$

$$d_{23} = (M_2 \cdot M_3) \quad d_{23} := \left[\frac{-1}{2} \cdot \frac{10}{7} \cdot 2 \left(\frac{1}{3} \cdot \frac{16}{5} + \frac{2}{3} \cdot \frac{87}{35} \right) - \frac{1}{2} \cdot \frac{10}{7} \cdot 2 \left(\frac{2}{3} \cdot \frac{87}{35} + \frac{1}{3} \cdot \frac{62}{35} \right) - \frac{1}{2} \cdot \frac{6}{7} \cdot 2 \left(\frac{1}{3} \cdot \frac{87}{35} + \frac{2}{3} \cdot \frac{62}{35} \right) \right] \dots = -10.016$$

$$+ \frac{1}{2} \cdot \frac{6}{7} \cdot \frac{5}{2} \cdot \left(\frac{-2}{3} \cdot \frac{62}{35} + \frac{1}{3} \cdot \frac{51}{140} \right) + \frac{1}{2} \cdot \frac{3}{7} \cdot \frac{5}{2} \cdot \left(\frac{-1}{3} \cdot \frac{62}{35} + \frac{2}{3} \cdot \frac{51}{140} \right) + \frac{1}{2} \cdot \frac{3}{7} \cdot \frac{5}{2} \cdot \frac{2}{3} \cdot \frac{51}{140}$$

$$d_{24} = (M_2 \cdot M_4) \quad d_{24} := \frac{1}{2} \cdot 2 \cdot \frac{10}{7} \cdot \left(\frac{12}{5} \right) + \frac{1}{2} \cdot \frac{10}{7} \cdot 2 \left(\frac{12}{5} \right) + \frac{1}{2} \cdot \frac{6}{7} \cdot 2 \left(\frac{12}{5} \right) + \frac{1}{2} \cdot 5 \cdot \frac{6}{7} \cdot \left(\frac{2}{3} \cdot \frac{12}{5} \right) = 12.343$$

$$d_{33} = (M_3 \cdot M_3) \quad d_{33} := \frac{1}{2} \cdot \frac{16}{5} \cdot 4 \cdot \frac{2}{3} \cdot \frac{16}{5} + \frac{1}{2} \cdot \frac{16}{5} \cdot 4 \cdot \left(\frac{2}{3} \cdot \frac{16}{5} + \frac{1}{3} \cdot \frac{62}{35} \right) + \frac{1}{2} \cdot \frac{62}{35} \cdot 4 \cdot \left(\frac{1}{3} \cdot \frac{16}{5} + \frac{2}{3} \cdot \frac{62}{35} \right) \dots = 41.347$$

$$+ \frac{1}{2} \cdot \frac{62}{35} \cdot \frac{5}{2} \cdot \left(\frac{2}{3} \cdot \frac{62}{35} - \frac{1}{3} \cdot \frac{51}{140} \right) + \frac{1}{2} \cdot \frac{51}{140} \cdot \frac{5}{2} \cdot \left(\frac{-1}{3} \cdot \frac{62}{35} + \frac{2}{3} \cdot \frac{51}{140} \right) + \frac{1}{2} \cdot \frac{51}{140} \cdot \frac{5}{2} \cdot \frac{2}{3} \cdot \frac{51}{140}$$

$$d_{34} = (M_3 \cdot M_4) \quad d_{34} := \frac{-1}{2} \cdot 4 \cdot \frac{12}{5} \cdot \frac{2}{3} \cdot \frac{16}{5} - \frac{12}{5} \cdot 4 \cdot \left(\frac{1}{2} \cdot \frac{16}{5} + \frac{1}{2} \cdot \frac{62}{35} \right) - \frac{1}{2} \cdot \frac{62}{35} \cdot \frac{5}{2} \cdot \left(\frac{2}{3} \cdot \frac{12}{5} + \frac{1}{3} \cdot \frac{6}{5} \right) \dots = -37.439$$

$$+ \frac{1}{2} \cdot \frac{51}{140} \cdot \frac{5}{2} \cdot \left(\frac{1}{3} \cdot \frac{12}{5} + \frac{2}{3} \cdot \frac{6}{5} \right) + \frac{1}{2} \cdot \frac{6}{5} \cdot \frac{5}{2} \cdot \frac{2}{3} \cdot \frac{51}{140}$$

$$d_{44} = (M_1 \cdot M_1) \quad d_{44} := \frac{1}{2} \cdot 4 \cdot \frac{12}{5} \cdot \frac{2}{3} \cdot \frac{12}{5} + \frac{12}{5} \cdot 4 \cdot \frac{12}{5} + \frac{1}{2} \cdot \frac{12}{5} \cdot 5 \cdot \frac{2}{3} \cdot \frac{12}{5} = 40.32$$

$$d_{21} := d_{12} \quad d_{42} := d_{24}$$

$$d_{31} := d_{13} \quad d_{43} := d_{34}$$

$$d_{41} := d_{14}$$

$$d_{32} := d_{23}$$

Masy na poszczególnych dynamicznych stopniach swobody

masa porównawcza $m_0 := 50 \cdot \text{kg}$

$$m_1 := 4 \quad m_2 := 4 \quad m_3 := 5 \quad m_4 := 5$$

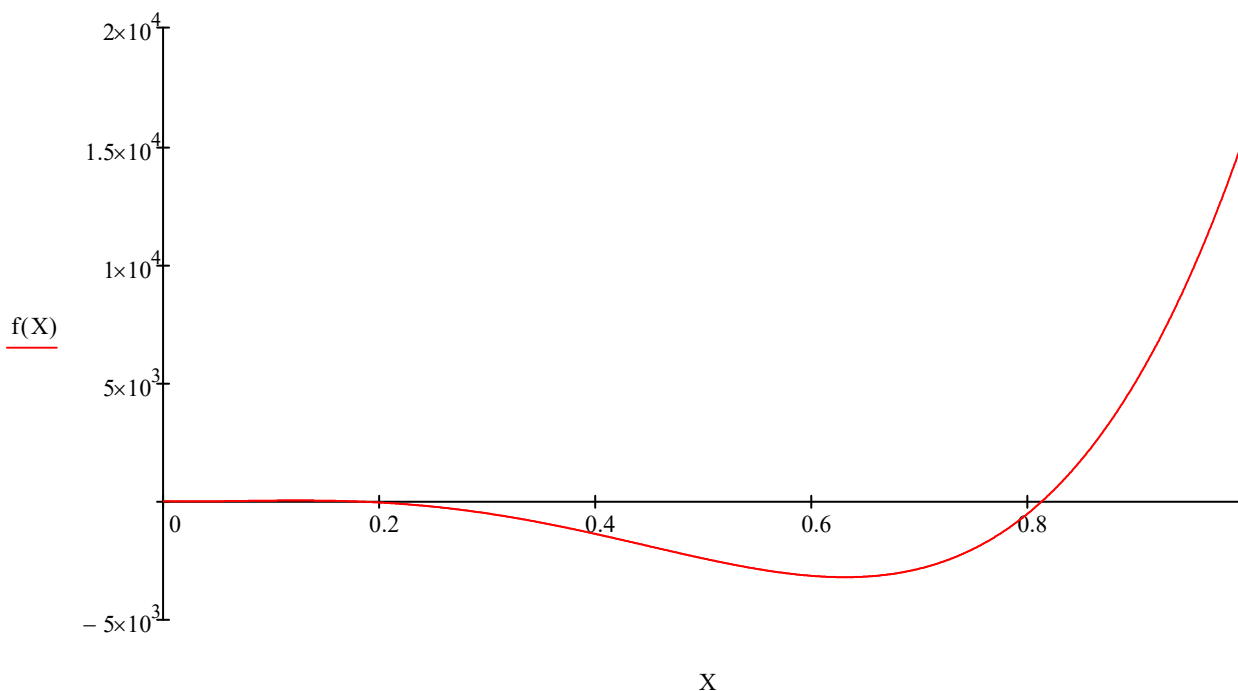
$$\begin{pmatrix} m_1 \cdot \frac{d_{11}}{EJ} - \frac{1}{\omega^2} & m_2 \cdot \frac{d_{12}}{EJ} & m_3 \cdot \frac{d_{13}}{EJ} & m_4 \cdot \frac{d_{14}}{EJ} \\ m_1 \cdot \frac{d_{21}}{EJ} & m_2 \cdot \frac{d_{22}}{EJ} - \frac{1}{\omega^2} & m_3 \cdot \frac{d_{23}}{EJ} & m_4 \cdot \frac{d_{24}}{EJ} \\ m_1 \cdot \frac{d_{31}}{EJ} & m_2 \cdot \frac{d_{32}}{EJ} & m_3 \cdot \frac{d_{33}}{EJ} - \frac{1}{\omega^2} & m_4 \cdot \frac{d_{34}}{EJ} \\ m_1 \cdot \frac{d_{41}}{EJ} & m_2 \cdot \frac{d_{42}}{EJ} & m_3 \cdot \frac{d_{43}}{EJ} & m_4 \cdot \frac{d_{44}}{EJ} - \frac{1}{\omega^2} \end{pmatrix} \cdot \begin{pmatrix} A_1 \\ A_2 \\ A_3 \\ A_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

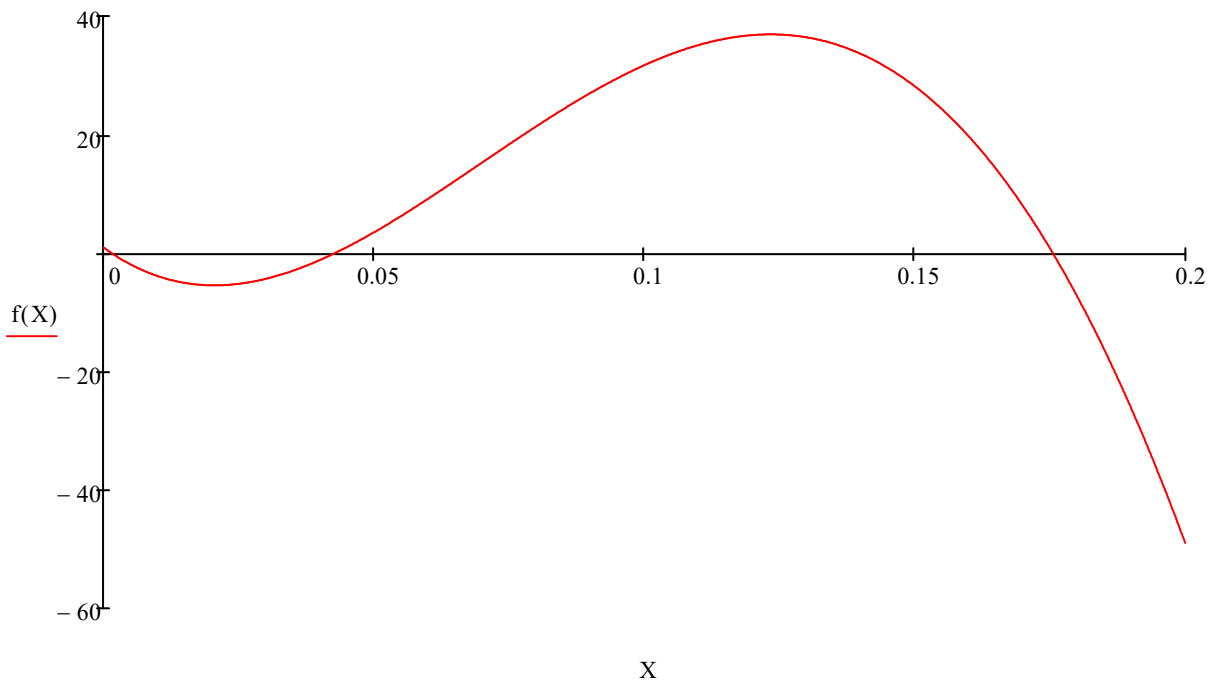
$$X = \frac{m_0 \cdot m^3 \cdot \omega}{EJ}$$

$$\begin{pmatrix} m_1 \cdot d_{11} \cdot X - 1 & m_2 \cdot d_{12} \cdot X & m_3 \cdot d_{13} \cdot X & m_4 \cdot d_{14} \cdot X \\ m_1 \cdot d_{21} \cdot X & m_2 \cdot d_{22} \cdot X - 1 & m_3 \cdot d_{23} \cdot X & m_4 \cdot d_{24} \cdot X \\ m_1 \cdot d_{31} \cdot X & m_2 \cdot d_{32} \cdot X & m_3 \cdot d_{33} \cdot X - 1 & m_4 \cdot d_{34} \cdot X \\ m_1 \cdot d_{41} \cdot X & m_2 \cdot d_{42} \cdot X & m_3 \cdot d_{43} \cdot X & m_4 \cdot d_{44} \cdot X - 1 \end{pmatrix} \cdot \begin{pmatrix} A_1 \\ A_2 \\ A_3 \\ A_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$a(X) := \begin{pmatrix} m_1 \cdot d_{11} \cdot X - 1 & m_2 \cdot d_{12} \cdot X & m_3 \cdot d_{13} \cdot X & m_4 \cdot d_{14} \cdot X \\ m_1 \cdot d_{21} \cdot X & m_2 \cdot d_{22} \cdot X - 1 & m_3 \cdot d_{23} \cdot X & m_4 \cdot d_{24} \cdot X \\ m_1 \cdot d_{31} \cdot X & m_2 \cdot d_{32} \cdot X & m_3 \cdot d_{33} \cdot X - 1 & m_4 \cdot d_{34} \cdot X \\ m_1 \cdot d_{41} \cdot X & m_2 \cdot d_{42} \cdot X & m_3 \cdot d_{43} \cdot X & m_4 \cdot d_{44} \cdot X - 1 \end{pmatrix}$$

$$f(X) := -671.845663265306178 \cdot X + 19559.481575963745506 \cdot X^2 + -108215.5328798190812 \cdot X^3 + 104852.60770975207187 \cdot X^4 +$$





$$\text{roz}(X) := |a(X)|$$

$$\text{roz}(X) \rightarrow -671.845663265306178 \cdot X + 19559.481575963745506 \cdot X^2 + -108215.5328798190812 \cdot X^3 + 104852.60770975207187 \cdot X^4$$

$$X := 1$$

Given

$$|a(X)| = 0$$

$$\underline{X} := (\text{Find}(X)) \rightarrow (0.81205504899715134103 \quad 0.17552859606136613151 \quad 0.042930689844557922351 \quad -4.77260847658712142)$$

$$X = (0.812 \quad 0.176 \quad 0.043 \quad 1.559 \times 10^{-3})$$

$$\omega_1 := \sqrt{X_{1,4}} \cdot \sqrt{\frac{E \cdot \text{J}}{m_0 \cdot \text{m}^3}} \quad \omega_1 = 11.442 \frac{1}{\text{s}} \quad [\text{rad/s}] \quad f_1 := \frac{\omega_1}{2\pi} = 1.821 \cdot \text{Hz}$$

$$\omega_2 := \sqrt{X_{1,3}} \cdot \sqrt{\frac{E \cdot \text{J}}{m_0 \cdot \text{m}^3}} \quad \omega_2 = 60.051 \frac{1}{\text{s}} \quad [\text{rad/s}] \quad f_2 := \frac{\omega_2}{2\pi} = 9.557 \cdot \text{Hz}$$

$$\omega_3 := \sqrt{X_{1,2}} \cdot \sqrt{\frac{E \cdot \text{J}}{m_0 \cdot \text{m}^3}} \quad \omega_3 = 121.427 \frac{1}{\text{s}} \quad [\text{rad/s}] \quad f_3 := \frac{\omega_3}{2\pi} = 19.326 \cdot \text{Hz}$$

$$\omega_4 := \sqrt{X_{1,1}} \cdot \sqrt{\frac{E \cdot \text{J}}{m_0 \cdot \text{m}^3}} \quad \omega_4 = 261.175 \frac{1}{\text{s}} \quad [\text{rad/s}] \quad f_4 := \frac{\omega_4}{2\pi} = 41.567 \cdot \text{Hz}$$

$$\begin{array}{cccc}
d_{11} := d_{11} \cdot \frac{m^3}{E \cdot J} & d_{21} := d_{21} \cdot \frac{m^3}{E \cdot J} & d_{31} := d_{31} \cdot \frac{m^3}{E \cdot J} & d_{41} := d_{41} \cdot \frac{m^3}{E \cdot J} \\
d_{12} := d_{12} \cdot \frac{m^3}{E \cdot J} & d_{22} := d_{22} \cdot \frac{m^3}{E \cdot J} & d_{32} := d_{32} \cdot \frac{m^3}{E \cdot J} & d_{42} := d_{42} \cdot \frac{m^3}{E \cdot J} \\
d_{13} := d_{13} \cdot \frac{m^3}{E \cdot J} & d_{23} := d_{23} \cdot \frac{m^3}{E \cdot J} & d_{33} := d_{33} \cdot \frac{m^3}{E \cdot J} & d_{43} := d_{43} \cdot \frac{m^3}{E \cdot J} \\
d_{14} := d_{14} \cdot \frac{m^3}{E \cdot J} & d_{24} := d_{24} \cdot \frac{m^3}{E \cdot J} & d_{34} := d_{34} \cdot \frac{m^3}{E \cdot J} & d_{44} := d_{44} \cdot \frac{m^3}{E \cdot J}
\end{array}$$

Wyliczenie amplitud drgań własnych

$$m_1 := m_1 \cdot m_0 \quad m_2 := m_2 \cdot m_0 \quad m_3 := m_3 \cdot m_0 \quad m_4 := m_4 \cdot m_0$$

Dla $\omega_1 = 11.442 \frac{1}{s}$ [rad/s]

$$A_1 := 1 \quad A_2 := 1 \quad A_3 := 1 \quad A_4 := 1$$

Given

$$\left[m_1 \cdot d_{11} - \frac{1}{(\omega_1)^2} \right] \cdot A_1 + m_2 \cdot d_{12} \cdot A_2 + m_3 \cdot d_{13} \cdot A_3 + m_4 \cdot d_{14} \cdot A_4 = 0$$

$$m_1 \cdot d_{21} \cdot A_1 + \left(m_2 d_{22} - \frac{1}{\omega_1^2} \right) \cdot A_2 + m_3 \cdot d_{23} \cdot A_3 + m_4 \cdot d_{24} \cdot A_4 = 0$$

$$m_1 \cdot d_{31} \cdot A_1 + m_2 \cdot d_{32} \cdot A_2 + \left(m_3 d_{33} - \frac{1}{\omega_1^2} \right) \cdot A_3 + m_4 \cdot d_{34} \cdot A_4 = 0$$

$$P := \text{Find}(A_2, A_3, A_4) \rightarrow \begin{pmatrix} 0.22533943885124369444 \\ -0.81538460812406907968 \\ 0.80018938878466942192 \end{pmatrix}$$

$$A_{11} := 1$$

$$A_{21} := P_{1,1} = 0.225$$

$$A_{31} := P_{2,1} = -0.815$$

$$A_{41} := P_{3,1} = 0.8$$

$$P = \begin{pmatrix} 0.225 \\ -0.815 \\ 0.8 \end{pmatrix}$$

Dla $\omega_2 = 60.051 \frac{1}{s}$ [rad/s]

$$A_1 := 1 \quad A_2 := 1 \quad A_3 := 1 \quad A_4 := 1$$

Given

$$\left[m_1 \cdot d_{11} - \frac{1}{(\omega_2)^2} \right] \cdot A_1 + m_2 \cdot d_{12} \cdot A_2 + m_3 \cdot d_{13} \cdot A_3 + m_4 \cdot d_{14} \cdot A_4 = 0$$

$$m_1 \cdot d_{21} \cdot A_1 + \left(m_2 d_{22} - \frac{1}{\omega_2^2} \right) \cdot A_2 + m_3 \cdot d_{23} \cdot A_3 + m_4 \cdot d_{24} \cdot A_4 = 0$$

$$m_1 \cdot d_{31} \cdot A_1 + m_2 \cdot d_{32} \cdot A_2 + \left(m_3 d_{33} - \frac{1}{\omega_2^2} \right) \cdot A_3 + m_4 \cdot d_{34} \cdot A_4 = 0$$

$$P := \text{Find}(A_2, A_3, A_4)$$

$$A_{12} := 1$$

$$A_{22} := P_{1,1} = -2.178$$

$$A_{32} := P_{2,1} = -1.811$$

$$A_{42} := P_{3,1} = -2.354$$

$$\text{Dla } \omega_3 = 121.427 \frac{1}{\text{s}} \text{ [rad/s]}$$

$$\underline{A_1} := 1 \quad \underline{A_2} := 1 \quad \underline{A_3} := 1 \quad \underline{A_4} := 1$$

Given

$$\left[m_1 \cdot d_{11} - \frac{1}{(\omega_3)^2} \right] \cdot A_1 + m_2 \cdot d_{12} \cdot A_2 + m_3 \cdot d_{13} \cdot A_3 + m_4 \cdot d_{14} \cdot A_4 = 0$$

$$m_1 \cdot d_{21} \cdot A_1 + \left(m_2 d_{22} - \frac{1}{\omega_3^2} \right) \cdot A_2 + m_3 \cdot d_{23} \cdot A_3 + m_4 \cdot d_{24} \cdot A_4 = 0$$

$$m_1 \cdot d_{31} \cdot A_1 + m_2 \cdot d_{32} \cdot A_2 + \left(m_3 d_{33} - \frac{1}{\omega_3^2} \right) \cdot A_3 + m_4 \cdot d_{34} \cdot A_4 = 0$$

$$P := \text{Find}(A_2, A_3, A_4)$$

$$A_{13} := 1$$

$$A_{23} := P_{1,1} = -1.084$$

$$A_{33} := P_{2,1} = 1.061$$

$$A_{43} := P_{3,1} = 0.326$$

$$\text{Dla } \omega_4 = 261.175 \frac{1}{\text{s}} \text{ [rad/s]}$$

$$\underline{A_1} := 1 \quad \underline{A_2} := 1 \quad \underline{A_3} := 1 \quad \underline{A_4} := 1$$

Given

$$\left[m_1 \cdot d_{11} - \frac{1}{(\omega_4)^2} \right] \cdot A_1 + m_2 \cdot d_{12} \cdot A_2 + m_3 \cdot d_{13} \cdot A_3 + m_4 \cdot d_{14} \cdot A_4 = 0$$

$$m_1 \cdot d_{21} \cdot A_1 + \left(m_2 d_{22} - \frac{1}{\omega_4^2} \right) \cdot A_2 + m_3 \cdot d_{23} \cdot A_3 + m_4 \cdot d_{24} \cdot A_4 = 0$$

$$m_1 \cdot d_{31} \cdot A_1 + m_2 \cdot d_{32} \cdot A_2 + \left(m_3 d_{33} - \frac{1}{\omega_4^2} \right) \cdot A_3 + m_4 \cdot d_{34} \cdot A_4 = 0$$

$$P := \text{Find}(A_2, A_3, A_4)$$

$$A_{14} := 1$$

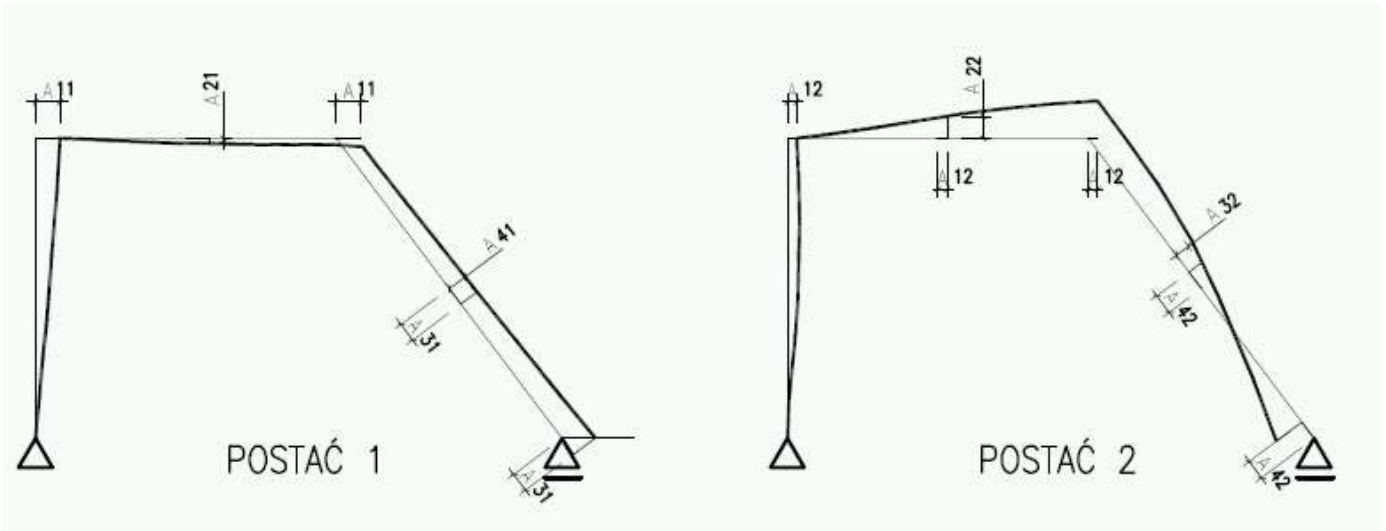
$$A_{24} := P_{1,1} = 1.131$$

$$A_{34} := P_{2,1} = 0.424$$

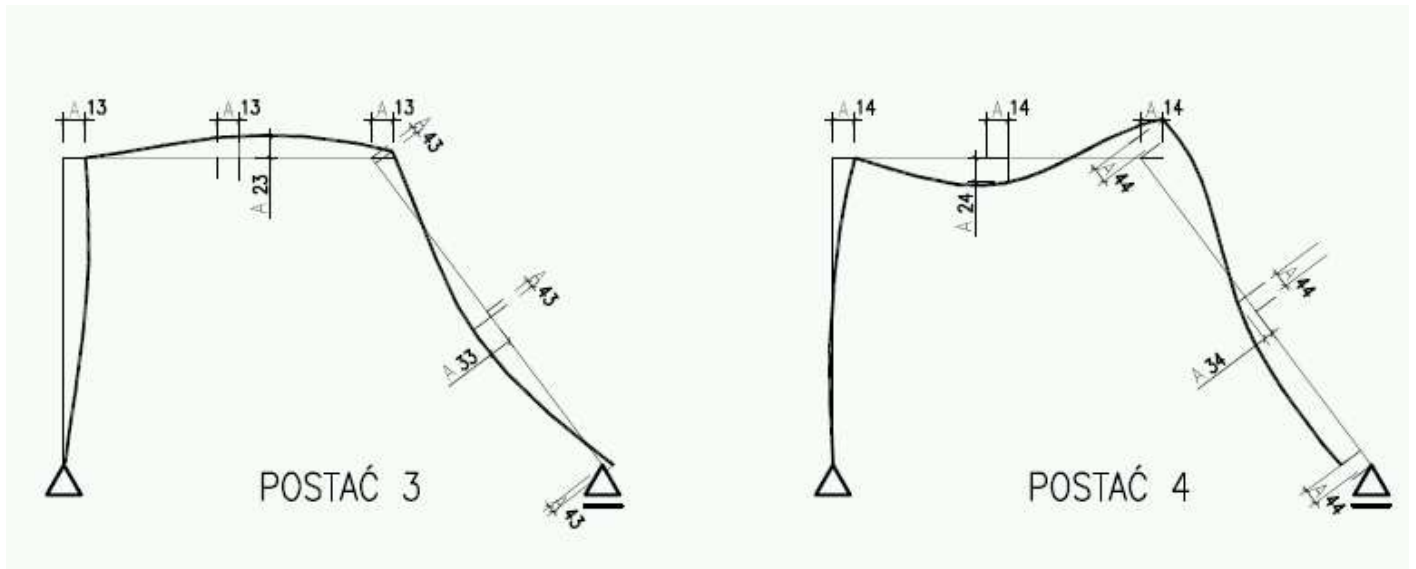
$$A_{44} := P_{3,1} = -0.823$$

Postacie drgań

Postać pierwsza i druga

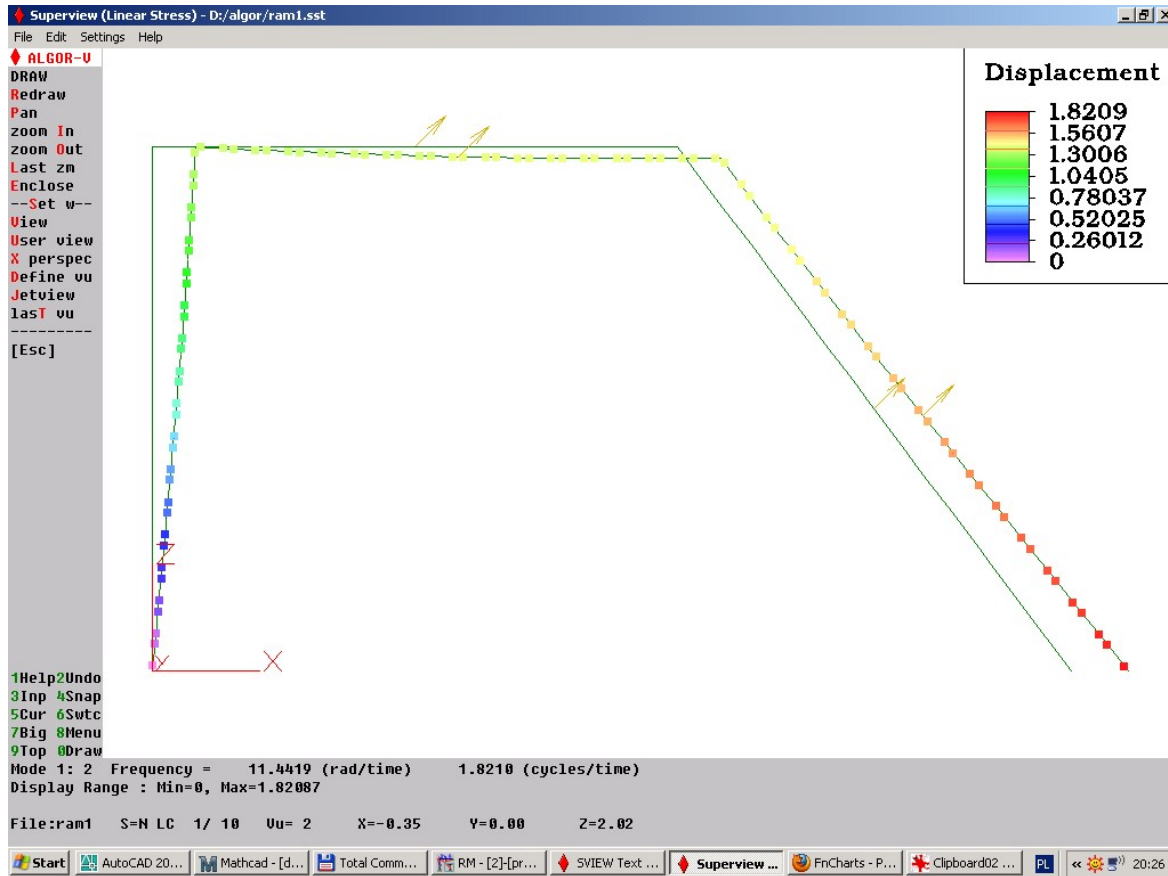


Postać trzecia oraz czwarta

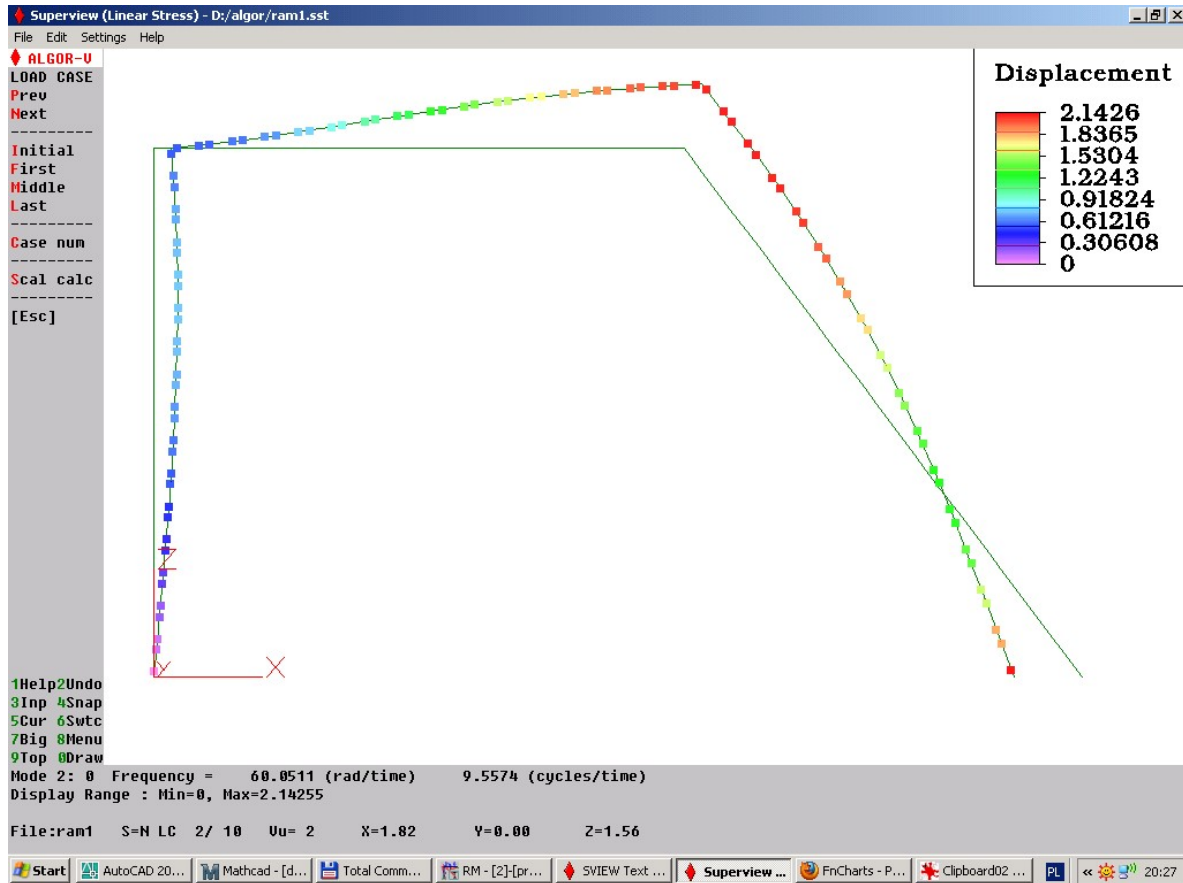


Postacie z programu ALGOR

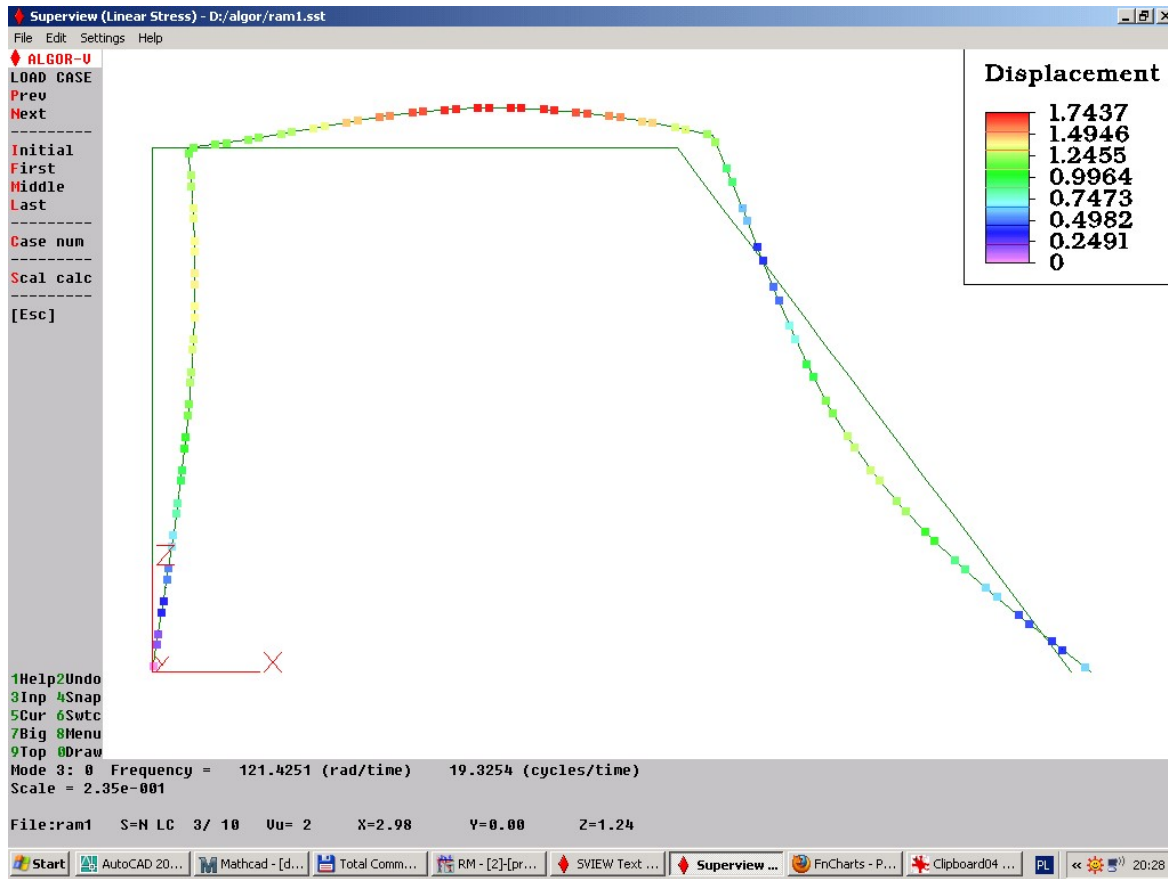
Postać pierwsza



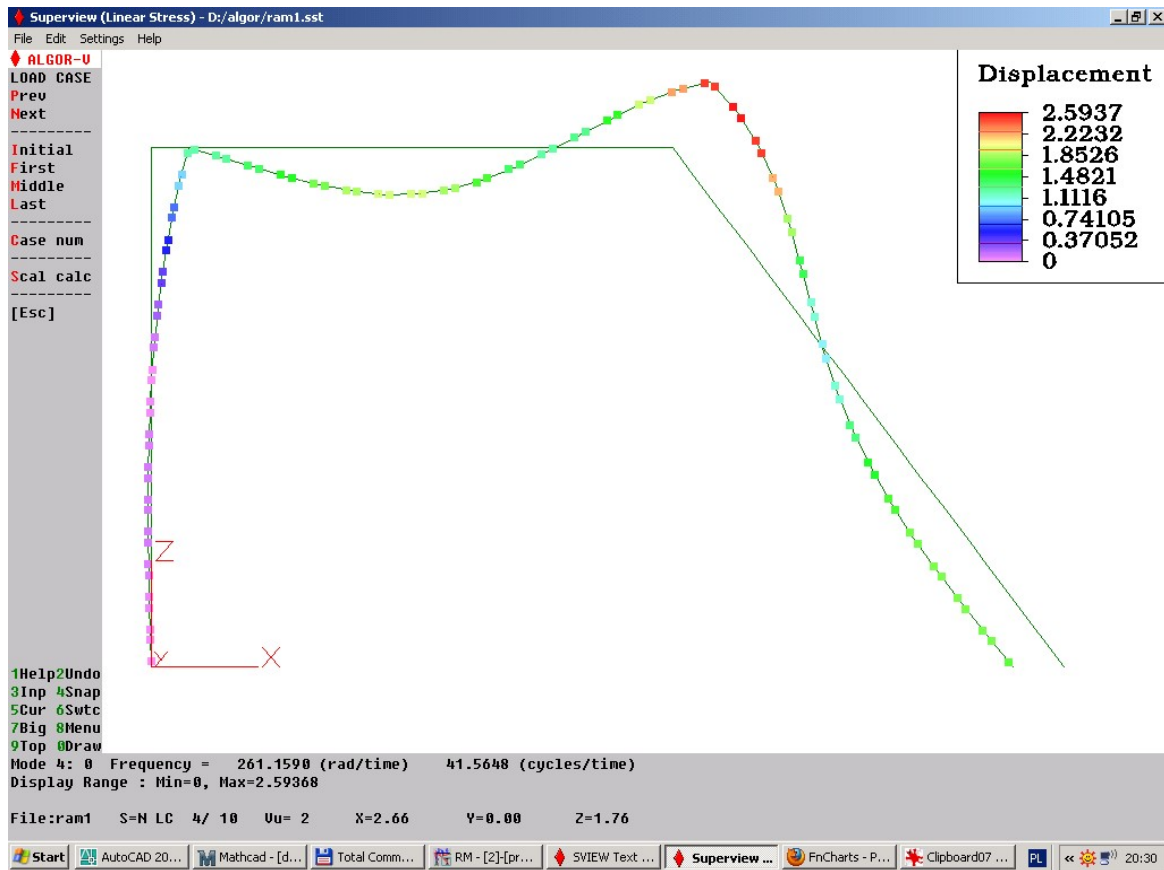
Postać druga



Postać trzecia



Postać czwarta



Warunek ortogonalności drgań

$$m_1 \cdot A_{11} \cdot A_{12} + m_2 \cdot A_{21} \cdot A_{22} + m_3 \cdot A_{31} \cdot A_{32} + m_4 \cdot A_{41} \cdot A_{42} = -5.684 \times 10^{-14} \text{ kg} \quad \text{sprawdzenie postaci 1 i 2}$$

$$m_1 \cdot A_{11} \cdot A_{13} + m_2 \cdot A_{21} \cdot A_{23} + m_3 \cdot A_{31} \cdot A_{33} + m_4 \cdot A_{41} \cdot A_{43} = -1.279 \times 10^{-13} \text{ kg} \quad \text{sprawdzenie postaci 1 i 3}$$

$$m_1 \cdot A_{11} \cdot A_{14} + m_2 \cdot A_{21} \cdot A_{24} + m_3 \cdot A_{31} \cdot A_{34} + m_4 \cdot A_{41} \cdot A_{44} = 2.842 \times 10^{-14} \text{ kg} \quad \text{sprawdzenie postaci 1 i 4}$$

$$m_1 \cdot A_{12} \cdot A_{13} + m_2 \cdot A_{22} \cdot A_{23} + m_3 \cdot A_{32} \cdot A_{33} + m_4 \cdot A_{42} \cdot A_{43} = 3.979 \times 10^{-12} \text{ kg} \quad \text{sprawdzenie postaci 2 i 3}$$

$$m_1 \cdot A_{12} \cdot A_{14} + m_2 \cdot A_{22} \cdot A_{24} + m_3 \cdot A_{32} \cdot A_{34} + m_4 \cdot A_{42} \cdot A_{44} = -2.501 \times 10^{-12} \text{ kg} \quad \text{sprawdzenie postaci 2 i 4}$$

$$m_1 \cdot A_{13} \cdot A_{14} + m_2 \cdot A_{23} \cdot A_{24} + m_3 \cdot A_{33} \cdot A_{34} + m_4 \cdot A_{43} \cdot A_{44} = -1.45 \times 10^{-12} \text{ kg} \quad \text{sprawdzenie postaci 3 i 4}$$

Metoda Dunkerlaya $\omega_1 = 11.442 \frac{1}{s}$

$$\omega_D = \frac{1}{\sqrt{\sum_i (m_i \cdot \delta_{ii})}}$$

$$\omega_D := \frac{1}{\sqrt{m_1 \cdot d_{11} + m_2 \cdot d_{22} + m_3 \cdot d_{33} + m_4 \cdot d_{44}}}$$

$$\omega_D = 11.182 \frac{1}{s}$$

Metoda Reyleigh'a $\omega_1 = 11.442 \frac{1}{s}$

$$\omega_R = \sqrt{\frac{E_{pmax}}{E_k}}$$

$$P := 1$$

$$P_1 := P$$

$$P_2 := P$$

$$P_3 := P$$

$$P_4 := P$$

$$E_{pmax} = \frac{1}{2} \cdot ((P_1 \cdot Y_1 + P_2 \cdot Y_2 + P_3 \cdot Y_3 + P_4 \cdot Y_4)) \quad P = P_1 = P_2 = P_3$$

$$E_{kmax} = \frac{1}{2} \cdot (m_1 \cdot Y_1^2 + m_2 \cdot Y_2^2 + m_3 \cdot Y_3^2 + m_4 \cdot Y_4^2) \quad y(t) = Y \cdot \sin \cdot \omega \cdot t$$

$$Y_1 := P \cdot (d_{11} + d_{12} + d_{13} + d_{14}) \quad Y_1 = 1.695 \times 10^{-5} \frac{s^2}{kg}$$

$$Y_2 := P \cdot (d_{21} + d_{22} + d_{23} + d_{24}) \quad Y_2 = 4.759 \times 10^{-6} \frac{s^2}{kg}$$

$$Y_3 := P \cdot (d_{31} + d_{32} + d_{33} + d_{34}) \quad Y_3 = -1.311 \times 10^{-5} \frac{s^2}{kg}$$

$$Y_4 := P \cdot (d_{41} + d_{42} + d_{43} + d_{44}) \quad Y_4 = 1.484 \times 10^{-5} \frac{s^2}{kg}$$

$$E_{pmax} := \frac{1}{2} \cdot (P_1 \cdot Y_1 + P_2 \cdot Y_2 + P_3 \cdot Y_3 + P_4 \cdot Y_4) \quad E_{pmax} = \frac{1}{85350} \frac{s^2}{kg}$$

$$E_k := \frac{1}{2} \cdot (m_1 \cdot Y_1^2 + m_2 \cdot Y_2^2 + m_3 \cdot Y_3^2 + m_4 \cdot Y_4^2) \quad E_k = \frac{1}{12504494} \frac{s^4}{kg}$$

$$\omega_R := \sqrt{\frac{E_{pmax}}{E_k}} \quad \omega_R = 12.104 \frac{1}{s}$$

$$Y_{1w} := (m_1 \cdot d_{11} + m_2 \cdot d_{12} + m_3 \cdot d_{13} + m_4 \cdot d_{14}) \quad Y_1 = 3.367 \times 10^{-3} \text{ s}^2$$

$$Y_{2w} := (m_1 \cdot d_{21} + m_2 \cdot d_{22} + m_3 \cdot d_{23} + m_4 \cdot d_{24}) \quad Y_2 = 9.795 \times 10^{-4} \text{ s}^2$$

$$Y_{3w} := (m_1 \cdot d_{31} + m_2 \cdot d_{32} + m_3 \cdot d_{33} + m_4 \cdot d_{34}) \quad Y_3 = -2.575 \times 10^{-3} \text{ s}^2$$

$$Y_{4w} := (m_1 \cdot d_{41} + m_2 \cdot d_{42} + m_3 \cdot d_{43} + m_4 \cdot d_{44}) \quad Y_4 = 3.001 \times 10^{-3} \text{ s}^2$$

$$E_{pmaxw} := (m_1 \cdot Y_1 + m_2 \cdot Y_2 + m_3 \cdot Y_3 + m_4 \cdot Y_4) \quad E_{pmax} = \frac{40}{41} \text{ s}^2 \cdot \text{kg}$$

$$E_{kw} := (m_1 \cdot Y_1^2 + m_2 \cdot Y_2^2 + m_3 \cdot Y_3^2 + m_4 \cdot Y_4^2) \quad E_k = \frac{1}{157} \text{ s}^4 \cdot \text{kg}$$

$$\omega_{Rw} := \sqrt{\frac{E_{pmax}}{E_k}} \quad \omega_R = 12.378 \frac{1}{\text{s}}$$

Sprawdzenie zakresu częstości

$$\omega_D = 11.182 \frac{1}{\text{s}} \quad \omega_1 = 11.442 \frac{1}{\text{s}} \quad \omega_R = 12.378 \frac{1}{\text{s}}$$

Drgania Wymuszone

liczba obrotów silnika	$n := \frac{30}{\text{s}}$		
częstość kołowa wymuszenia	$\Theta := 2 \cdot \pi \cdot n$	$\Theta = 188.496 \frac{1}{\text{s}}$	[rad/s]
masa wirnika	$mw := 40 \cdot \text{kg}$		
mimośród	$ew := 2 \text{cm}$		
amplituda drgań wymuszonych	$P_0 := mw \cdot ew \cdot \Theta^2$	$P_0 = 28.424 \cdot \text{kN}$	

Sprawdzenie rezonansu

1 częstość drgań własnych	$\omega_1 = 11.442 \frac{1}{\text{s}}$	$0.9 \cdot \omega_1 = 10.298 \frac{1}{\text{s}}$	$1.1 \cdot \omega_1 = 12.586 \frac{1}{\text{s}}$
2 częstość drgań własnych	$\omega_2 = 60.051 \frac{1}{\text{s}}$	$0.9 \cdot \omega_2 = 54.046 \frac{1}{\text{s}}$	$1.1 \cdot \omega_2 = 66.057 \frac{1}{\text{s}}$
3 częstość drgań własnych	$\omega_3 = 121.427 \frac{1}{\text{s}}$	$0.9 \cdot \omega_3 = 109.284 \frac{1}{\text{s}}$	$1.1 \cdot \omega_3 = 133.569 \frac{1}{\text{s}}$
4 częstość drgań własnych	$\omega_4 = 261.175 \frac{1}{\text{s}}$	$0.9 \cdot \omega_4 = 235.058 \frac{1}{\text{s}}$	$1.1 \cdot \omega_4 = 287.293 \frac{1}{\text{s}}$
częstość drgań wymuszonych	$\Theta = 188.496 \frac{1}{\text{s}}$		

Częstość drgań wymuszonych nie pokrywa się z żadną częstością drgań własnych.
Nie grozi rezonans.

Wyznaczenie sił bezwładności

$$\Delta_{1p} := d_{21} \cdot P_0 = 0.084 \text{ m}$$

$$\Delta_{2p} := d_{22} \cdot P_0 = 0.036 \text{ m}$$

$$\Delta_{3p} := d_{23} \cdot P_0 = -0.068 \text{ m}$$

$$\Delta_{4p} := d_{24} \cdot P_0 = 0.084 \text{ m}$$

Układ równań

$$\begin{pmatrix} d_{11} - \frac{1}{m_1 \cdot \Theta^2} & d_{12} & d_{13} & d_{14} \\ d_{21} & d_{22} - \frac{1}{m_2 \cdot \Theta^2} & d_{23} & d_{24} \\ d_{31} & d_{32} & d_{33} - \frac{1}{m_3 \cdot \Theta^2} & d_{34} \\ d_{41} & d_{42} & d_{43} & d_{44} - \frac{1}{m_4 \cdot \Theta^2} \end{pmatrix} \cdot \begin{pmatrix} B_1 \\ B_2 \\ B_3 \\ B_4 \end{pmatrix} + \begin{pmatrix} \Delta_{1p} \\ \Delta_{2p} \\ \Delta_{3p} \\ \Delta_{4p} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$WS := \begin{pmatrix} d_{11} - \frac{1}{m_1 \cdot \Theta^2} & d_{12} & d_{13} & d_{14} \\ d_{21} & d_{22} - \frac{1}{m_2 \cdot \Theta^2} & d_{23} & d_{24} \\ d_{31} & d_{32} & d_{33} - \frac{1}{m_3 \cdot \Theta^2} & d_{34} \\ d_{41} & d_{42} & d_{43} & d_{44} - \frac{1}{m_4 \cdot \Theta^2} \end{pmatrix}$$

$$WS = \begin{pmatrix} 0.014 & 2.954 \times 10^{-3} & -0.012 & 0.011 \\ 2.954 \times 10^{-3} & 1.11 \times 10^{-3} & -2.385 \times 10^{-3} & 2.939 \times 10^{-3} \\ -0.012 & -2.385 \times 10^{-3} & 9.732 \times 10^{-3} & -8.914 \times 10^{-3} \\ 0.011 & 2.939 \times 10^{-3} & -8.914 \times 10^{-3} & 9.487 \times 10^{-3} \end{pmatrix} \cdot \frac{\text{m}}{\text{kN}}$$

$$WP := \begin{pmatrix} \Delta_{1p} \\ \Delta_{2p} \\ \Delta_{3p} \\ \Delta_{4p} \end{pmatrix}$$

$$WP = \begin{pmatrix} -0.084 \\ -0.036 \\ 0.068 \\ -0.084 \end{pmatrix} \text{ m}$$

Wektor rozwiązań układu

$$B := WS^{-1} \cdot WP$$

$$B = \begin{pmatrix} 26.32 \\ -13.052 \\ 17.472 \\ -19.447 \end{pmatrix} \cdot \text{kN}$$

Obliczenie sił statycznych

Przyspieszenie ziemskie

$$g = 9.807 \frac{\text{m}}{\text{s}^2}$$

Ciążar 2 masy

$$G2 := m_2 \cdot g = 1.961 \cdot \text{kN}$$

Ciążar 3 masy

$$G3 := m_3 \cdot g = 2.452 \cdot \text{kN}$$

$$P0 = 28.424 \cdot \text{kN}$$

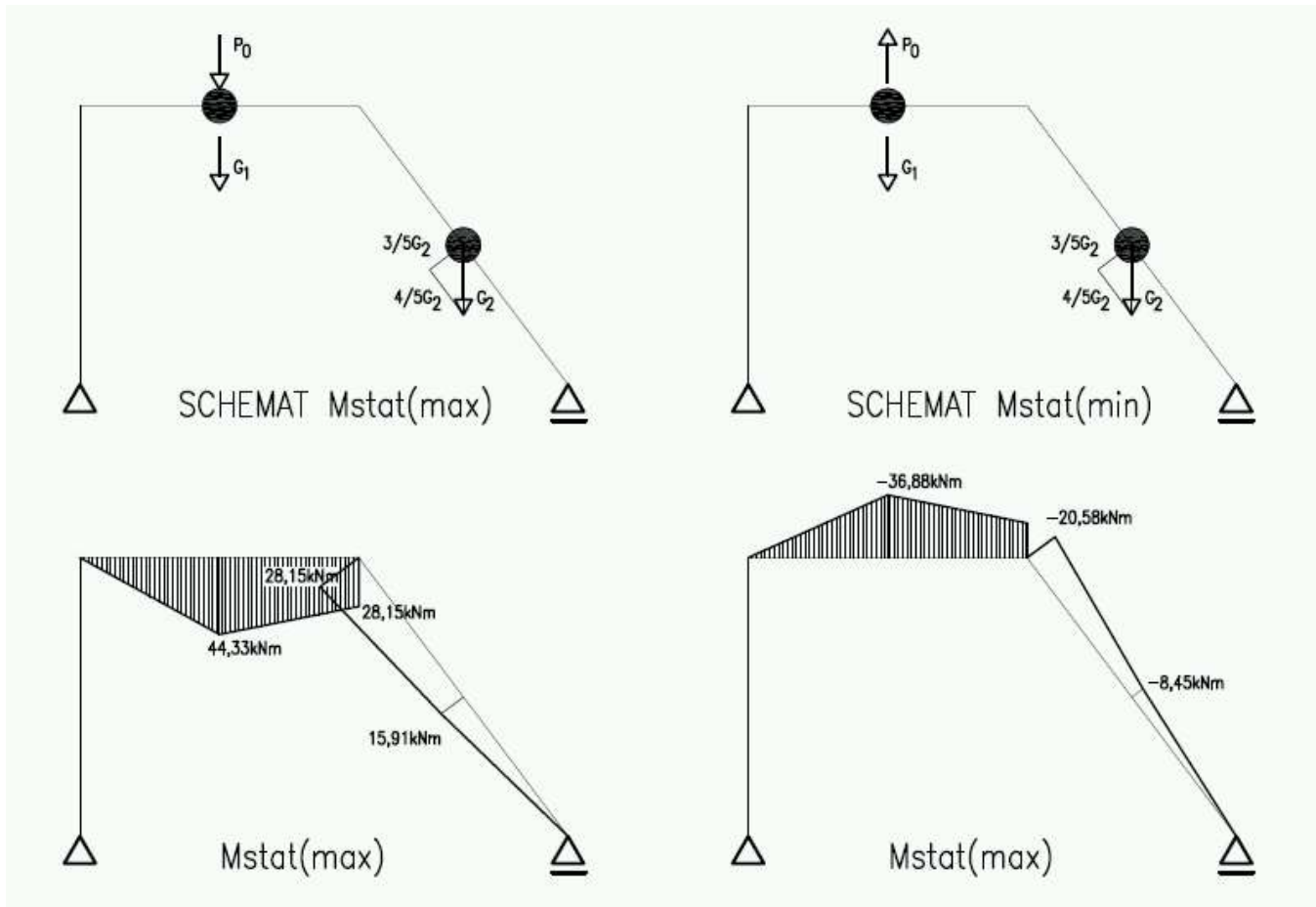
Momenty statyczne

$$M_{\text{st(max)}} = MB2 \cdot (P0 + G1) + MB3 \cdot \left(\frac{3}{5} G2\right) + MB4 \cdot \left(\frac{4}{5} G2\right)$$

$$M_{\text{st(min)}} = MB2 \cdot (-P0 + G1) + MB3 \cdot \left(\frac{3}{5} G2\right) + MB4 \cdot \left(\frac{4}{5} G2\right)$$

punkt	MB1	MB2	MB3	MB4	Mst(max)	Mst(min)
	[m]	[m]	[m]	[m]	[kNm]	[kNm]
A	0	0	0	0	0	0
B	4	0	-3,2	2,4	0	0
C	3,714286	1,428571	-2,57143	2,4	44,33351	-36,8779
D	1,714286	0,857143	-1,77143	2,4	28,14729	-20,5796
E	0,857143	0,428571	0,364286	1,2	15,91302	-8,45041
F	0	0	0	0	0	0

RYСУNEK



Momenty dynamiczne

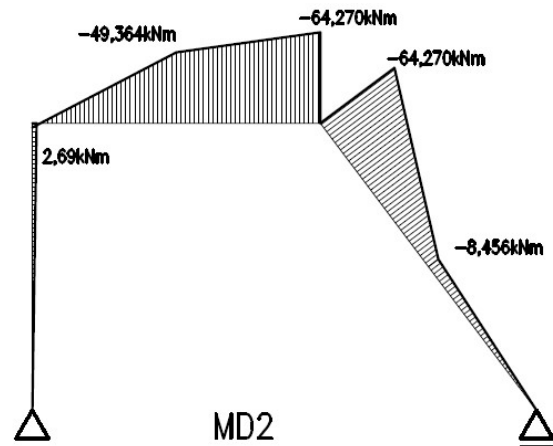
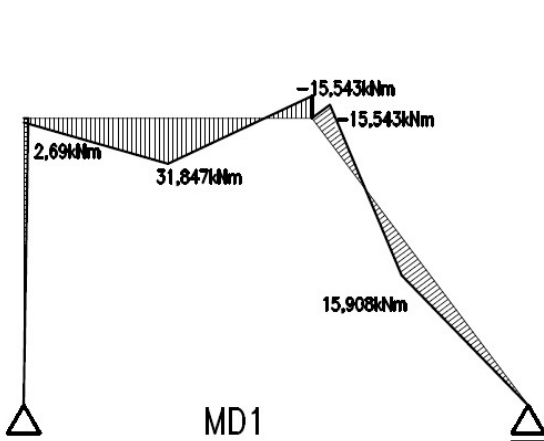
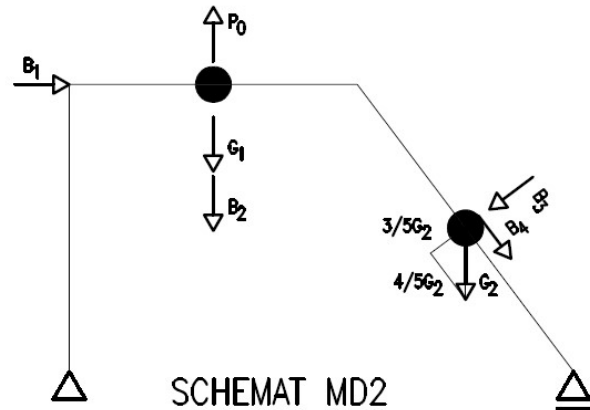
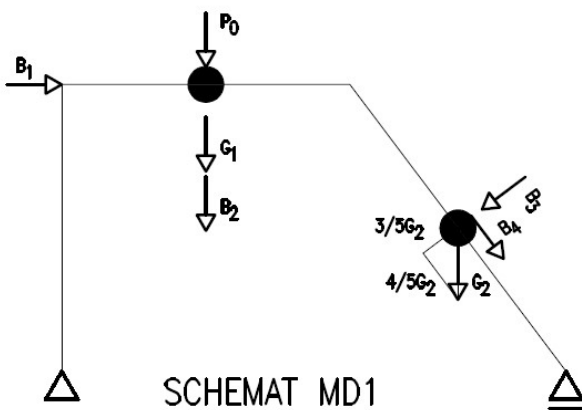
$$MD1 = MB1 \cdot B1 + MB2 \cdot (P0 + G1 + B2) + MB3 \cdot \left(\frac{3}{5}G2 + B3\right) + MB4 \cdot \left(\frac{4}{5}G2 + B4\right)$$

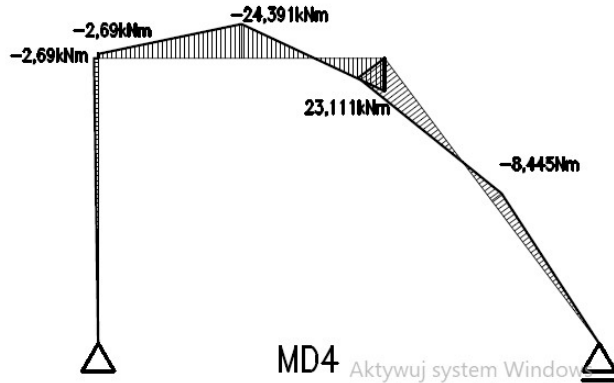
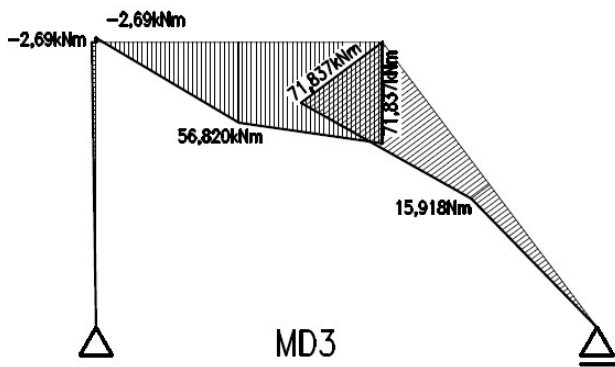
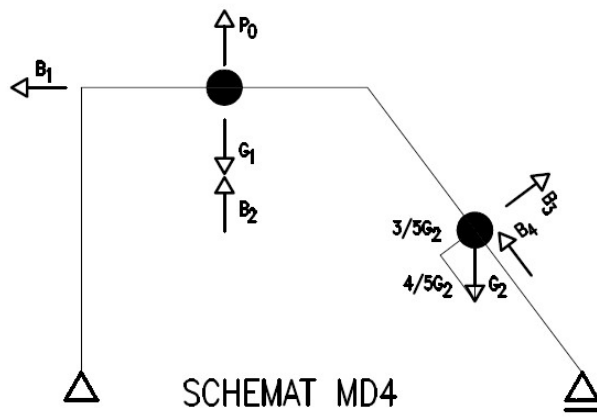
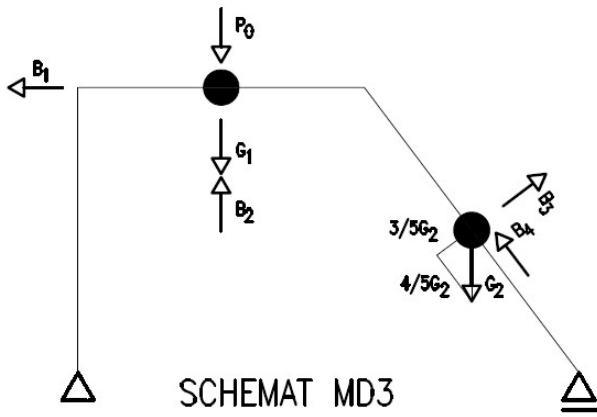
$$MD2 = MB1 \cdot B1 + MB2 \cdot (-P0 + G1 + B2) + MB3 \cdot \left(\frac{3}{5}G2 - B3\right) + MB4 \cdot \left(\frac{4}{5}G2 + B4\right)$$

$$MD3 = MB1 \cdot -B1 + MB2 \cdot (P0 + G1 - B2) + MB3 \cdot \left(\frac{3}{5}G2 - B3\right) + MB4 \cdot \left(\frac{4}{5}G2 - B4\right)$$

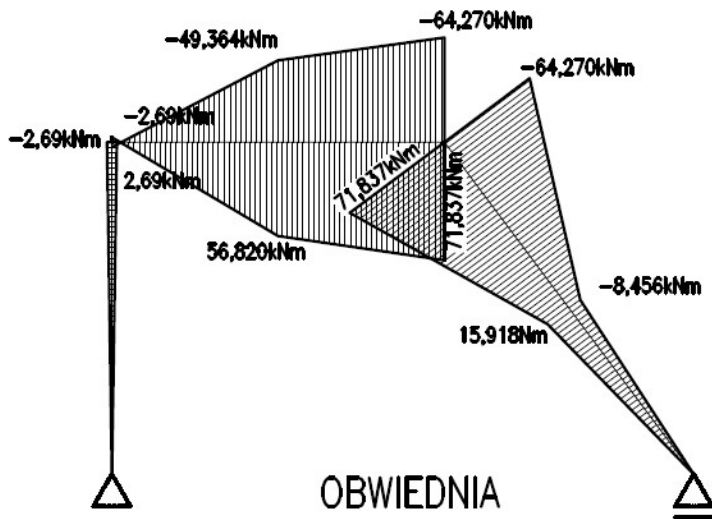
$$MD4 = MB1 \cdot -B1 + MB2 \cdot (-P0 + G1 - B2) + MB3 \cdot \left(\frac{3}{5}G2 - B3\right) + MB4 \cdot \left(\frac{4}{5}G2 - B4\right)$$

punkt	MB1	MB2	MB3	MB4	M1D	M2D	M3D	M4D	Mmax	Mmin
	[m]	[m]	[m]	[m]	[kNm]	[kNm]	[kNm]	[kNm]	[kNm]	[kNm]
A	0	0	0	0	0	0	0	0	0	0
B	4	0	-3,2	2,4	2,6968	2,6968	-2,6968	-2,6968	2,6968	-2,6968
C	3,714286	1,428571	-2,57143	2,4	31,847	-49,3644	56,82003	-24,3914	56,82003	-49,3644
D	1,714286	0,857143	-1,77143	2,4	-15,5433	-64,2702	71,83791	23,11106	71,83791	-64,2702
-	0,857143	0,428571	0,364286	1,2	15,9077	-8,45573	15,91833	-8,4451	15,91833	-8,45573
RYSUNEK	0	0	0	0	0	0	0	0	0	0





Aktywuj system Windows
Przejdź do ustawień, aby aktywować system



Wymiarowanie konstrukcji

$$J = 2 \times 10^{-5} \text{ m}^4$$

$$W_x := \frac{b \cdot h^2}{6} = 400 \cdot \text{cm}^3 \quad J = 2 \times 10^3 \cdot \text{cm}^4$$

$$M_{st} := 44 \text{ kN} \cdot \text{m}$$

$$M_D := 81.837 \cdot \text{kN} \cdot \text{m}$$

$$f_d := 355 \cdot \text{MPa}$$

$$f_{ddyn} := 0.6 \cdot f_d = 213 \cdot \text{MPa}$$

naprężenia

$$\sigma_{st} := \left| \frac{M_{st}}{W_x} \right|$$

$$\sigma_{st} = 110 \cdot \text{MPa}$$

$$\sigma_{st} < f_d = 1$$

warunek spełniony

$$\sigma_{dyn} := \left| \frac{M_D}{W_x} \right|$$

$$\sigma_{dyn} = 204.593 \cdot \text{MPa}$$

$$\sigma_{dyn} < f_{ddyn} = 1$$

warunek spełniony

+ 1.0

27e-29i 0.0015585457197518072671 + 4.7726084765871214227e-29i)

